

where $\boldsymbol{\gamma}_t = (\xi_t, \boldsymbol{\eta}_t^\top)^\top$ denotes the model parameters and $g_t(\boldsymbol{\eta}_t, \tilde{\mathbf{x}}_{it}, \tilde{\mathbf{y}}_{it})$ some functions of $(\boldsymbol{\eta}_t, \tilde{\mathbf{x}}_{it}, \tilde{\mathbf{y}}_{it})$. For example, if y_{it} and \mathbf{x}_{it} are all continuous, we can set $g_t(\boldsymbol{\eta}_t, \tilde{\mathbf{x}}_{it}, \tilde{\mathbf{y}}_{it}) = \boldsymbol{\eta}_{xt}^\top \tilde{\mathbf{x}}_{it} + \boldsymbol{\eta}_{yt}^\top \tilde{\mathbf{y}}_{it}$ with $\boldsymbol{\eta}_t = (\boldsymbol{\eta}_{xt}^\top, \boldsymbol{\eta}_{yt}^\top)^\top$. More complex forms of $g_t(\boldsymbol{\eta}_t, \tilde{\mathbf{x}}_{it}, \tilde{\mathbf{y}}_{it})$ as well as cases with other types of y_{it} and \mathbf{x}_{it} , such as binary, are similarly considered. Under MMDP, we have (see exercise):

$$\pi_{it}(\boldsymbol{\gamma}) = p_{it} \Pr(r_{i(t-1)} = 1 \mid H_{i(t-1)}) = \prod_{s=2}^t p_{is}(\boldsymbol{\gamma}_s), \quad (4.88)$$

$$2 \leq t \leq m, \quad 1 \leq i \leq n$$

where $\boldsymbol{\gamma} = (\boldsymbol{\gamma}_1^\top, \dots, \boldsymbol{\gamma}_m^\top)^\top$. Thus, we can estimate π_{it} from p_{it} in (4.87) using the above relationship.

Note that when modeled by (4.87) and (4.88), π_{it} in theory ranges between 0 and 1. However, \mathbf{x}_{it} can be assumed to be bounded and the requirement $\pi_{it} \geq c > 0$ is satisfied for all practical purposes. Note also that when π_{it} is estimated by (4.88), the asymptotic variance in (4.83) or (4.85) is likely to underestimate the variability of $\hat{\boldsymbol{\beta}}$. Unlike the parameter vector $\boldsymbol{\alpha}$ in G_i , the variability of $\hat{\boldsymbol{\gamma}}$ cannot be ignored even for \sqrt{n} -consistent estimate. If $\hat{\boldsymbol{\gamma}}$ is obtained from GEE or maximum likelihood method, we can readily find the asymptotic variance of $\hat{\boldsymbol{\beta}}$ obtained from (4.82) with $\boldsymbol{\gamma}$ substituted by $\hat{\boldsymbol{\gamma}}$.

Let $\hat{\boldsymbol{\gamma}}$ be the solution to the equation: $\mathbf{u}_n(\boldsymbol{\gamma}) = \sum_{i=1}^n \mathbf{u}_{ni}(\boldsymbol{\gamma}) = \mathbf{0}$, where \mathbf{u}_{ni} is the score (for maximum likelihood estimation) or score-like vector (for GEE estimation) for the i th subject ($1 \leq i \leq n$). As in the proof of Theorem 1 of Section 4.3.2, let \mathbf{u}_n and \mathbf{w}_n denote the normalized versions of \mathbf{u}_n and \mathbf{w}_n in (4.82), that is,

$$\mathbf{u}_n = \frac{1}{n} \sum_{i=1}^n \mathbf{u}_{ni}, \quad \mathbf{w}_n = \frac{1}{n} \sum_{i=1}^n \mathbf{w}_{ni} = \frac{1}{n} \sum_{i=1}^n G_i(\mathbf{x}_i) \Delta_i S_i$$

Then, by a Taylor series expansion, we have

$$\begin{aligned} \sqrt{n}(\hat{\boldsymbol{\gamma}} - \boldsymbol{\gamma}) &= \left(-\frac{\partial}{\partial \boldsymbol{\gamma}} \mathbf{u}_n \right)^{-\top} \sqrt{n} \mathbf{u}_n + \mathbf{o}_p(1) \\ &= -H^{-1} \frac{\sqrt{n}}{n} \sum_{i=1}^n \mathbf{u}_{ni} + \mathbf{o}_p(1) \end{aligned}$$